

ABSTRACT

A method for object detection using vehicle-mounted sensors is provided, the sensing ranges of which sensors overlap at least partially. In this context, signals of at least two sensors
5 having sensing ranges with essentially identical coverage, and additional signals of at least one additional sensor having a sensing range which only partially overlaps with the sensing ranges of the at least two sensors, are evaluated. An object is identified as relevant when it is detected by at least two
10 of the sensors.